How to make a smart camera pipeline

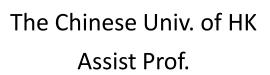
Tianfan Xue The Chinese University of Hong Kong



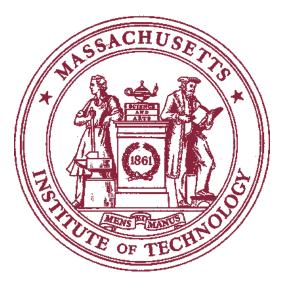
About myself







Google Research, Gcam Staff Eng. Manager: David Saleson 2017-2022



MIT Ph.D. Advisor: William T. Freeman 2012-2017

Smart camera = ML algorithms applied images?

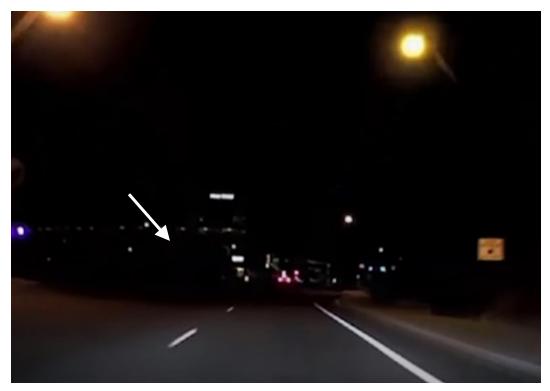




Object detection

Face beautification [Leyvand et al., 2006]

Camera may not capture visual signal for ML system



One frame



A frame 2s later

Images are too dark for ML to detect this biking person

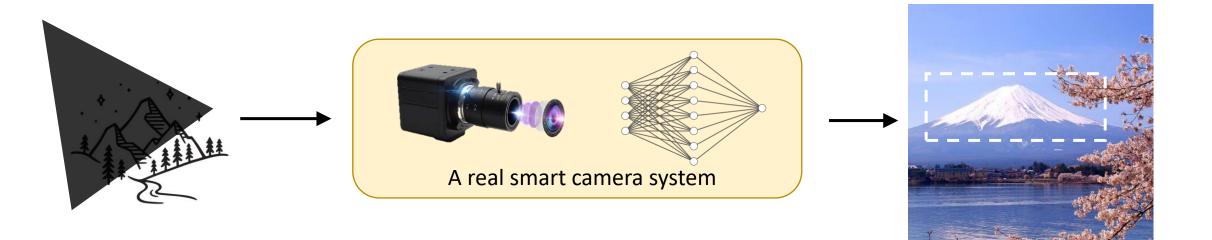
Video from a fatal car crash

Separate design may fail



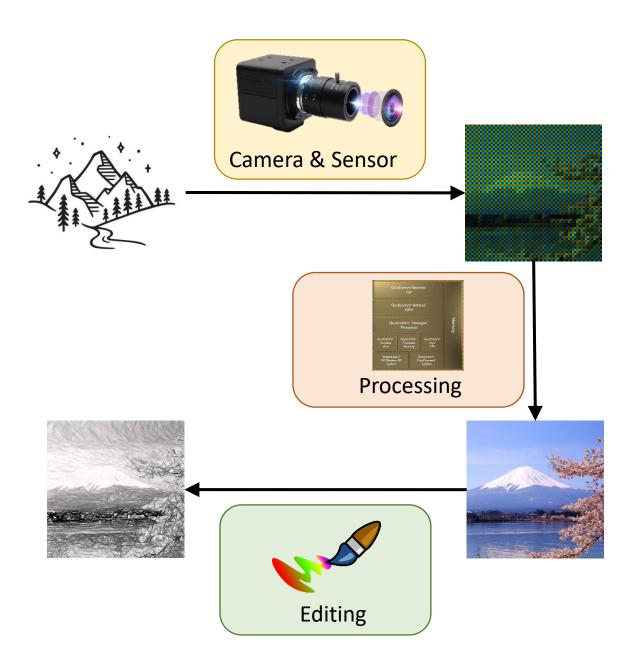
Machine learning embedded in the camera





Overview

- **Capturing**: multiple source fusion
- Processing & editing
 - Training data: synthetic data
 - Network: combine classic image processing algorithm and machine learning



Overview

- **Capturing**: multiple source fusion
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Image in lowlight



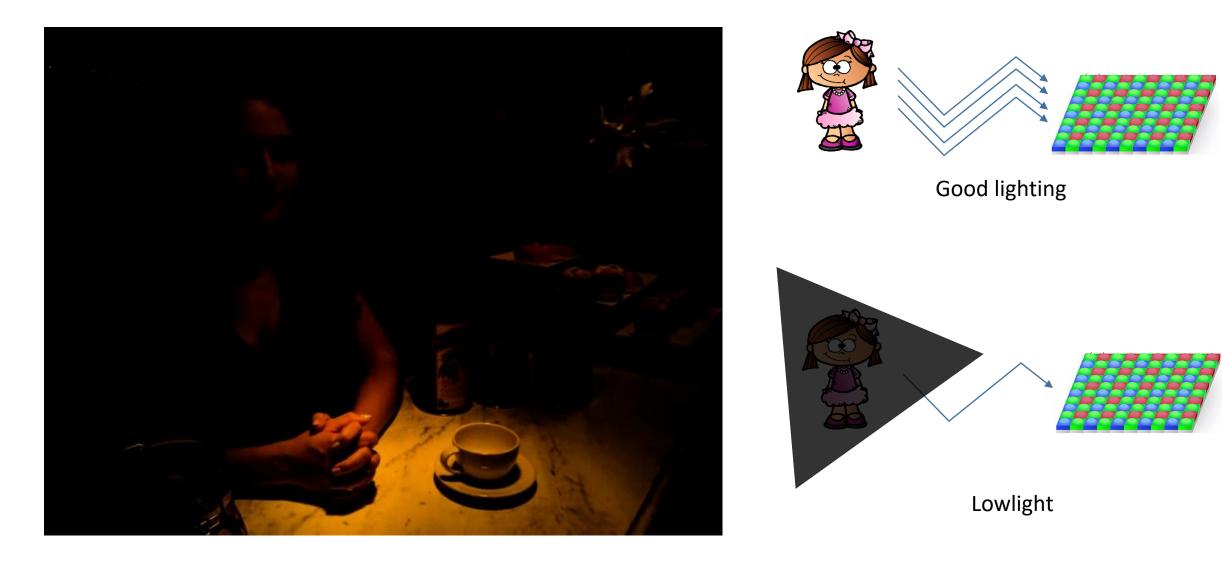
"Handheld Mobile Photography in Very Low Ligh", SIGGRAPH Asia 2019



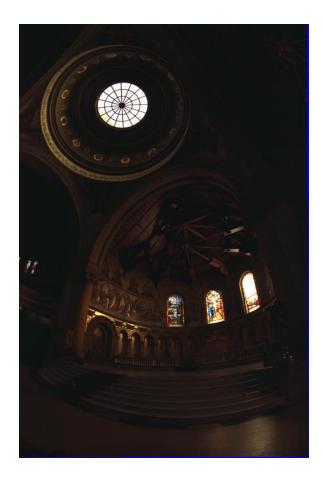
by our night sight algorithm

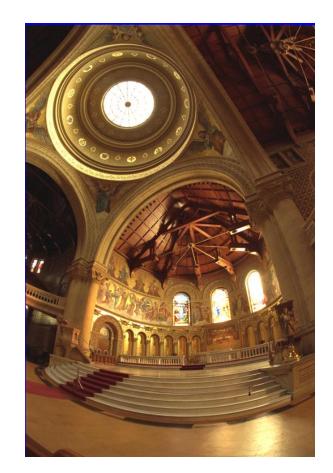


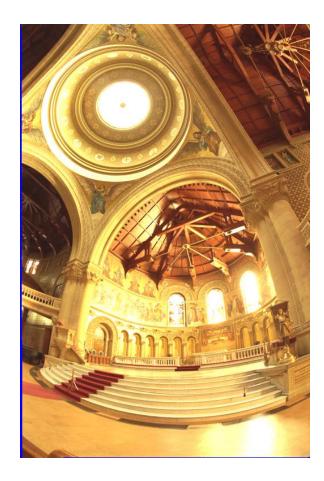
Not enough photons in lowlight



Exposure bracketing







[Debevec et al., 2007] [Gallo and Sen 2016]

From long exposure to burst photography





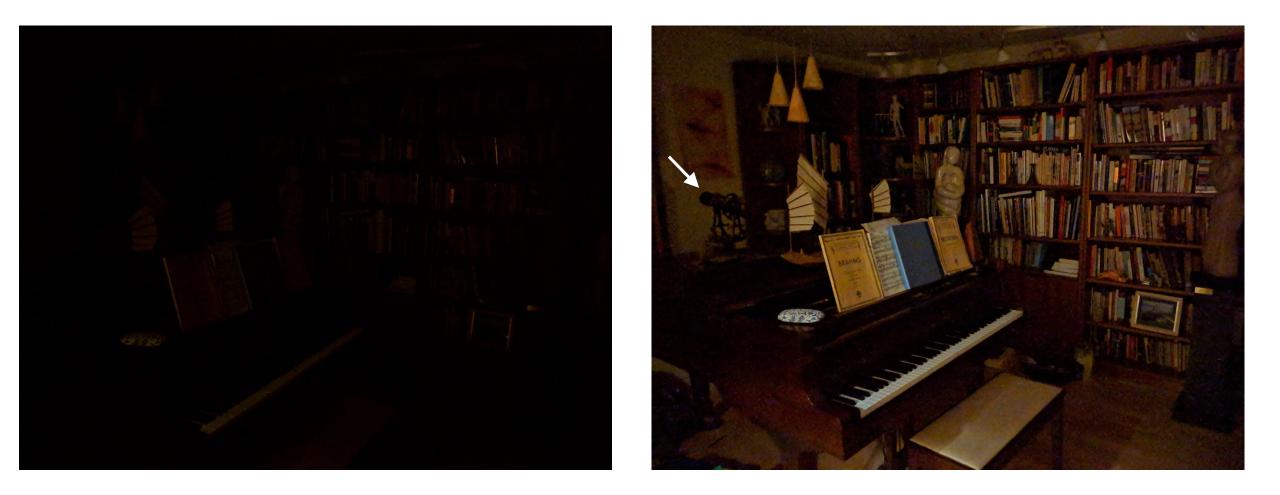
Long-exposure Motion blur Burst photography burst of short exposed frames HDR+





S. Hasinoff et al, "Burst photography for high dynamic range and low-light imaging on mobile cameras ", SIGGRAPH Asia 2016.

Night sight



O. Liba, et al., "Handheld Mobile Photography in Very Low Ligh", SIGGRAPH Asia 2019.

Multiple captures also helps to remove reflection



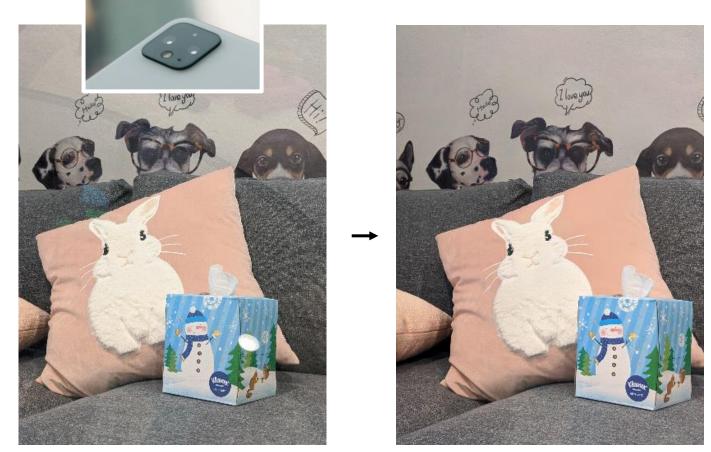
Images with reflection



Reflection-free image

T. Xue, et al., "A Computational Approach for Obstruction-Free Photography", SIGGRAPH, 2015.

Reflection removal using stereo input

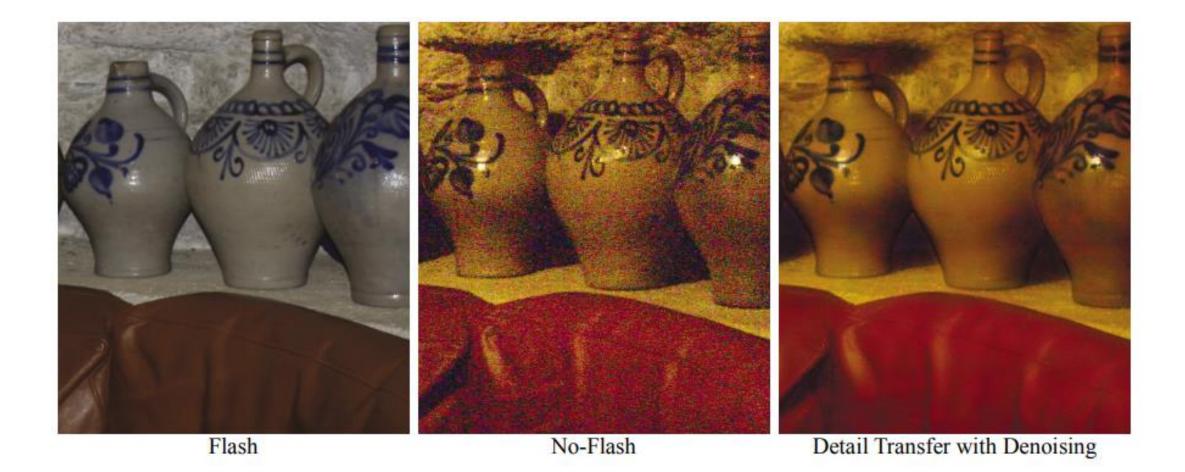


2 frames from stereo camera

Output

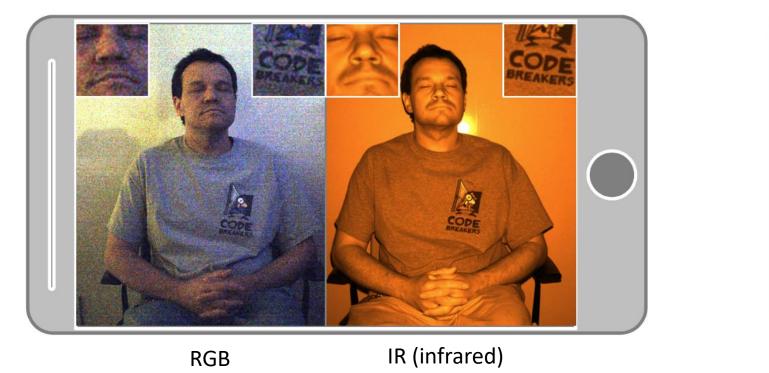
S. Niklaus et al., "Learned dual-view reflection removal", WACV, 2021.

Flash / Non-flash Photography



G. Petschnigg et al., "Digital Photography with Flash and No-Flash Image Pairs", SIGGRAPH 2004.

Stereoscopic Dark Flash for Low-light Photography



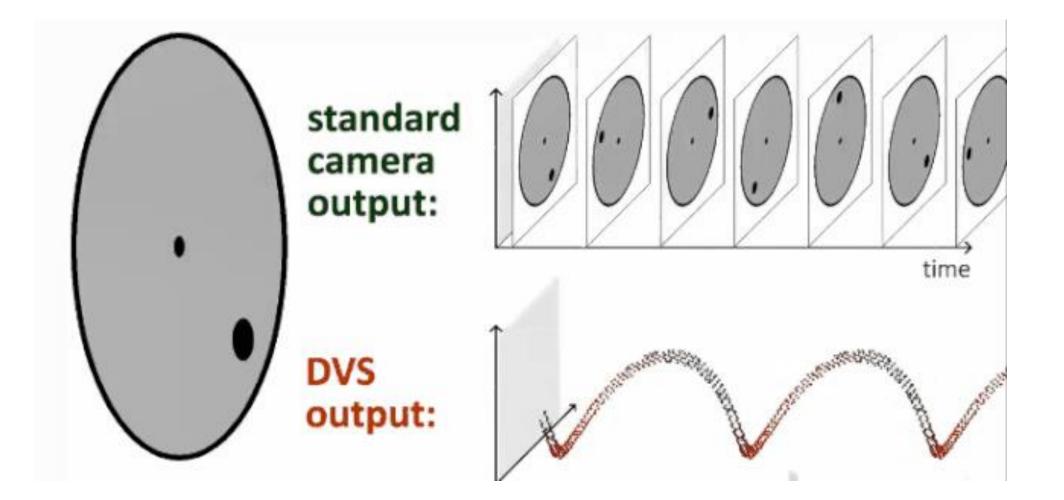


Merged result

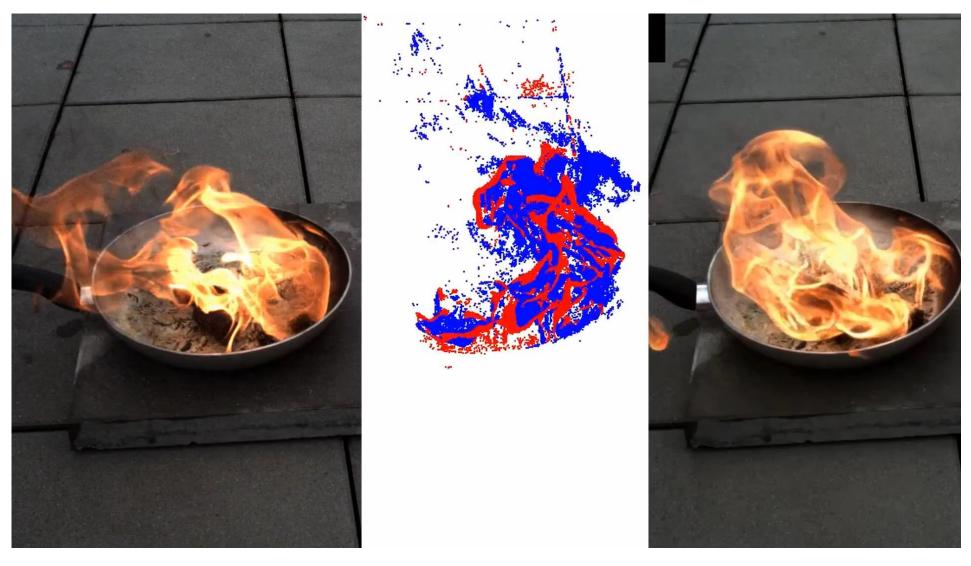
Jian Wang, Tianfan Xue, Jonathan T. Barron, Jiawen Chen

ICCP 2019

Event camera

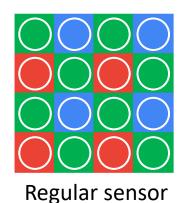


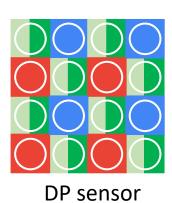
Use event camera to recover high-speed motion



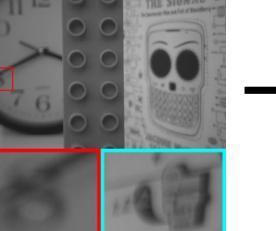
S. Tulyakov et al., "Time Lens: Event-based Video Frame Interpolation", CVPR 2021.

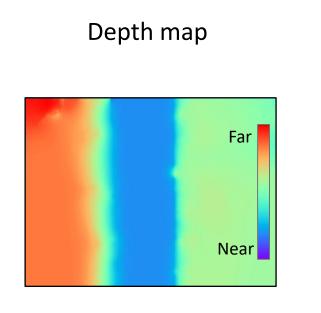
Depth and debluring from DP images



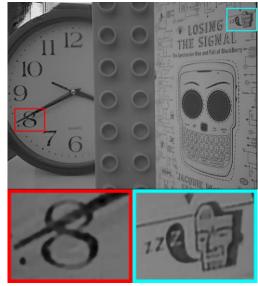


Input DP image





All-in-focus image



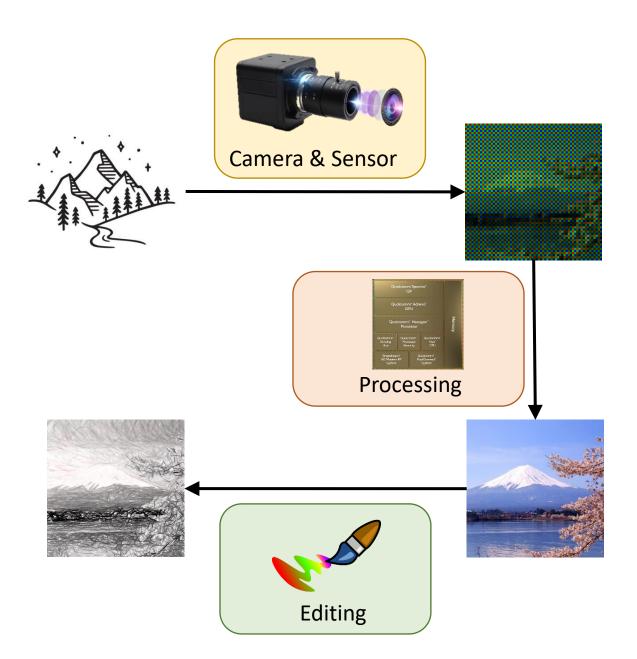
Defocus Map Estimation and Deblurring from a Single Dual-Pixel Image

S. Xin, N. Wadhwa, T. Xue, J. T. Barron, P. P. Srinivasan, J. Chen, I. Gkioulekas, R. Garg

ICCV 2021

Overview

- **Capturing**: multiple source fusion
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 - Training data: synthetic data
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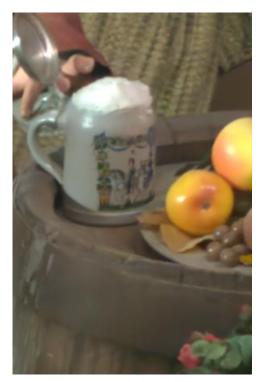


An input/output pair is needed for ML training

Neural network

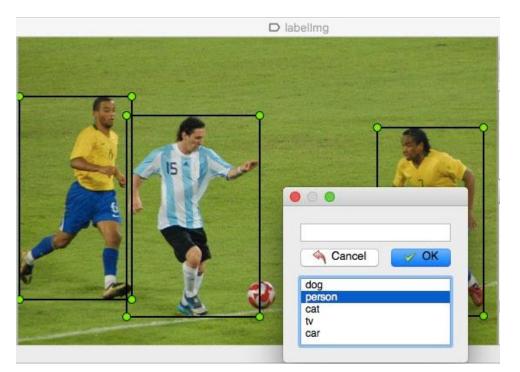


Noisy input



Denoised output

Ground truth output are hard to label





Labeling detection is **easy**. few seconds / image

Image Credit: https://github.com/tzutalin/labelImg

Label denoising is hard: few hours / image

Image Credit: Nik Collection

Capturing ground truth requires a lot of manual efforts



Collecting ground truth for denoising (<100/day)

Image Credit: [Chen et al. CVPR, 2018]

Devices differences



DSLR



Mobile camera



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2020-06-06

2020-06-06

List of Android smartphones

From Wikipedia, the free encyclopedia

This is a list of devices that run on the Android operating system

This is a dynamic list and may never be able to satisfy particular standards for completeness. You can help by adding missing items with reliable sources.

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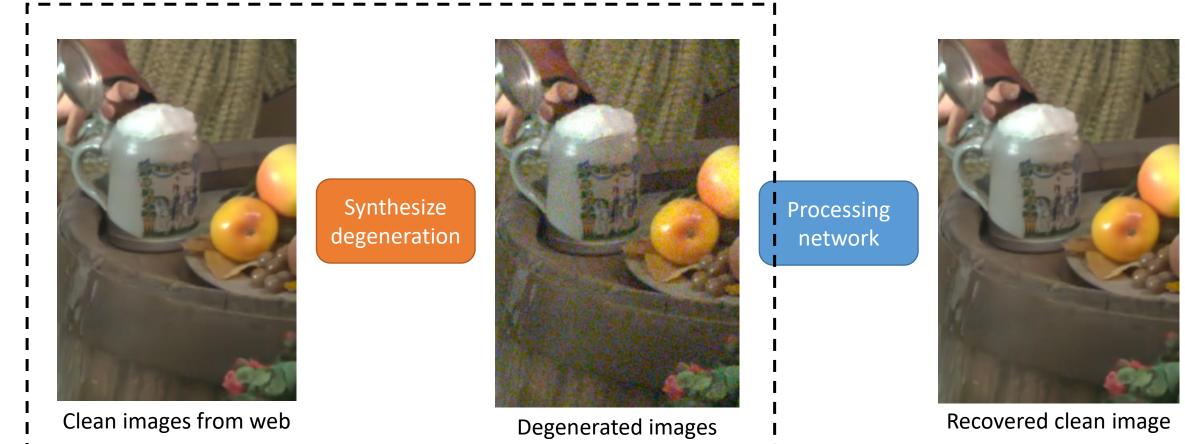


No. of images uploaded to internet: 3,000,000,000,000 images / day

by Leon Seibert, Unsplash

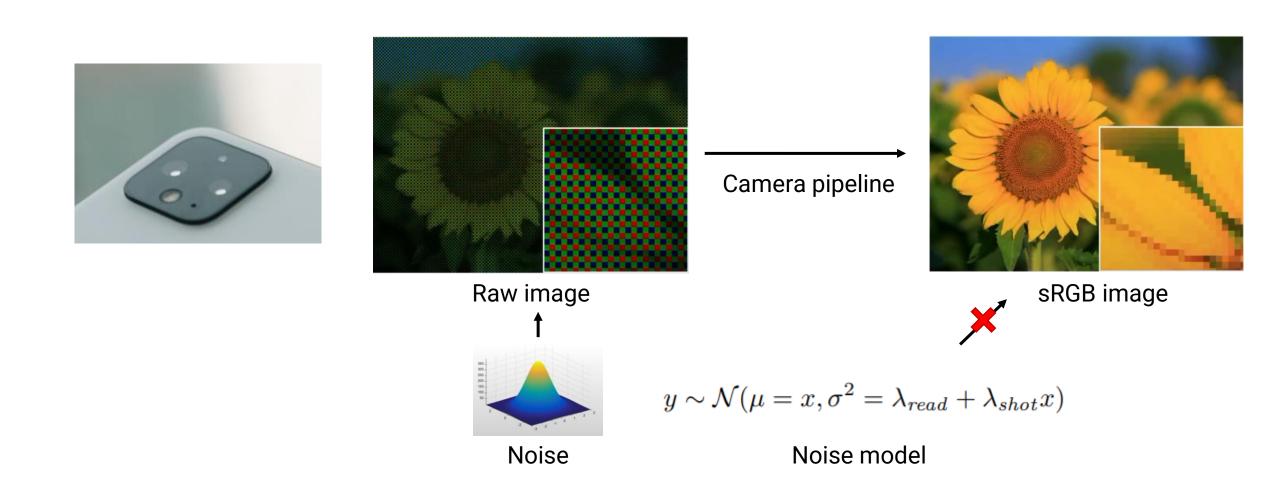
Apply degeneration to images on the web

Input/output pairs



How to generate realistic degeneration?

Real noise does not directly apply to sRGB



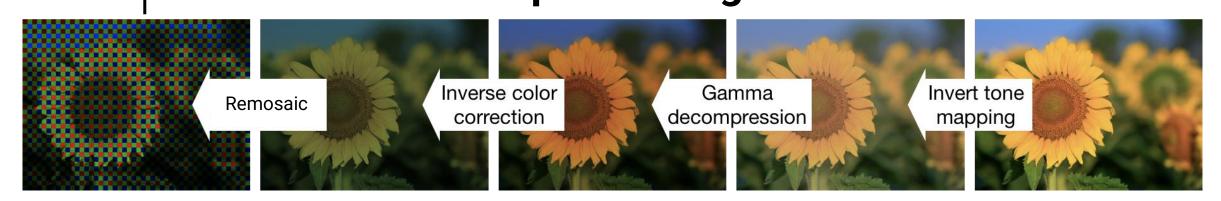
Synthesize raw from sRGB

"Reprocessing"

Raw sensor data

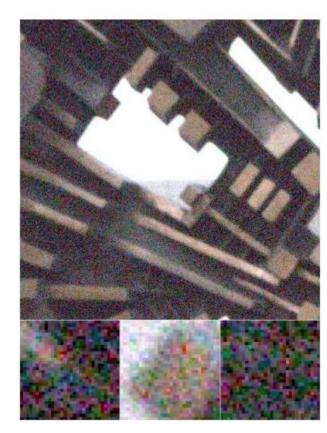
sRGB image



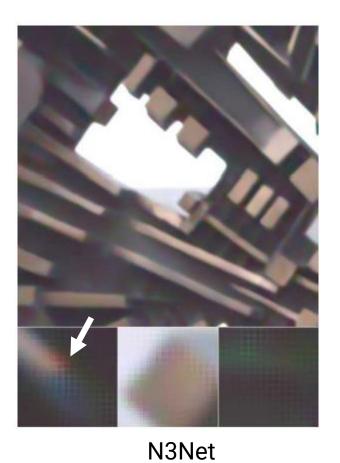


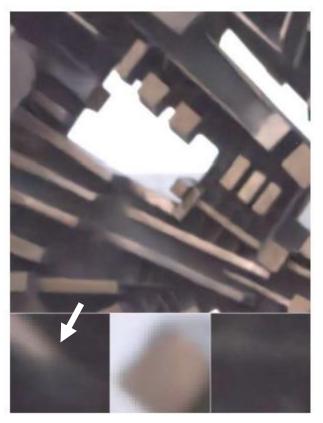
T. Brooks, B. Mildenhall, T. Xue, J. Chen, D. Sharlet, J. T. Barron, "Unprocessing images for learned raw denoising", CVPR, 2019

Unprocess improves the image quality



Noisy input





Ours

Simulate realistic rain drops

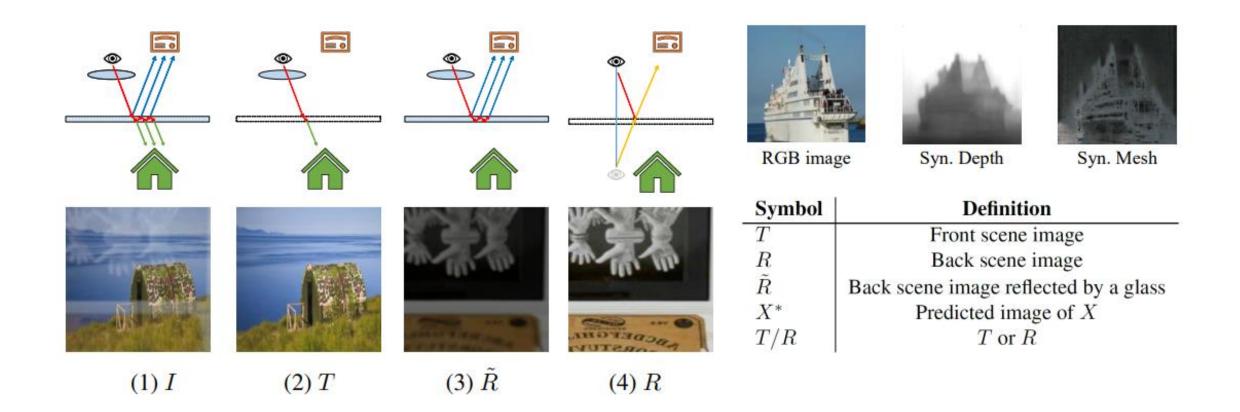


(a) Heavy rain.

(b) Rain acccumulation.

Yang et al., "Deep Joint Rain Detection and Removal from a Single Image", 2017

Sometimes, it is important to understand 3D geometry in the simulation



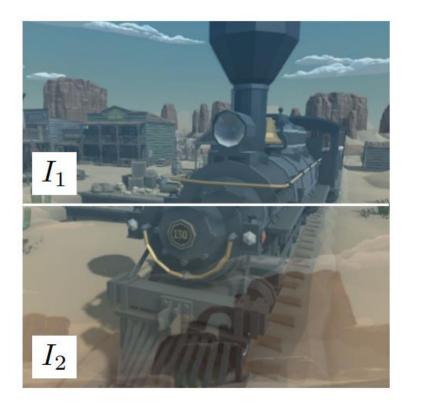
Kim et al., "Single Image Reflection Removal with Physically-Based Training Images", CVPR 2020

We can even resort to rendering engine



S. Niklaus et al., "Learned dual-view reflection removal", WACV, 2021.

We can even resort to rendering engine



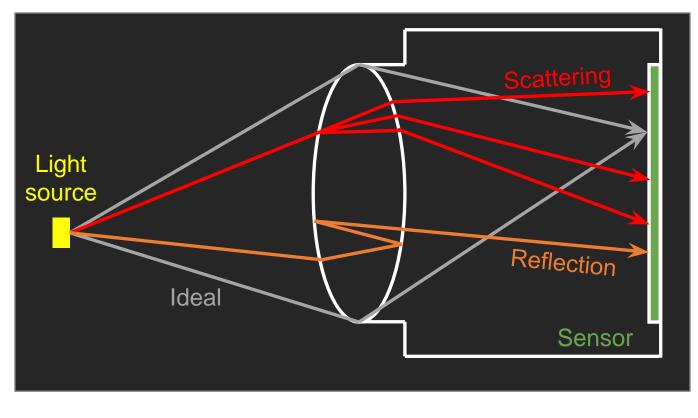


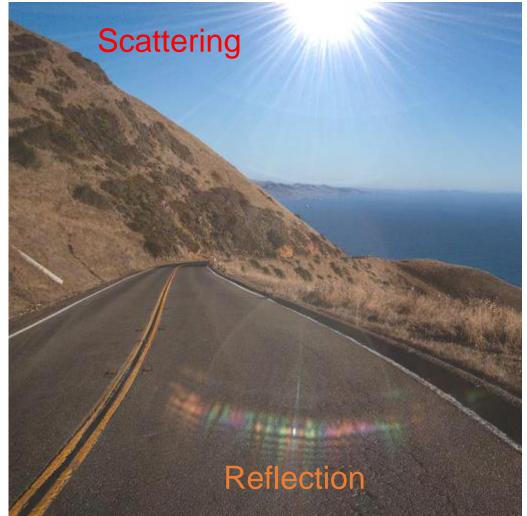
S. Niklaus et al., "Learned dual-view reflection removal", WACV, 2021.

Lens flare



Flare formation

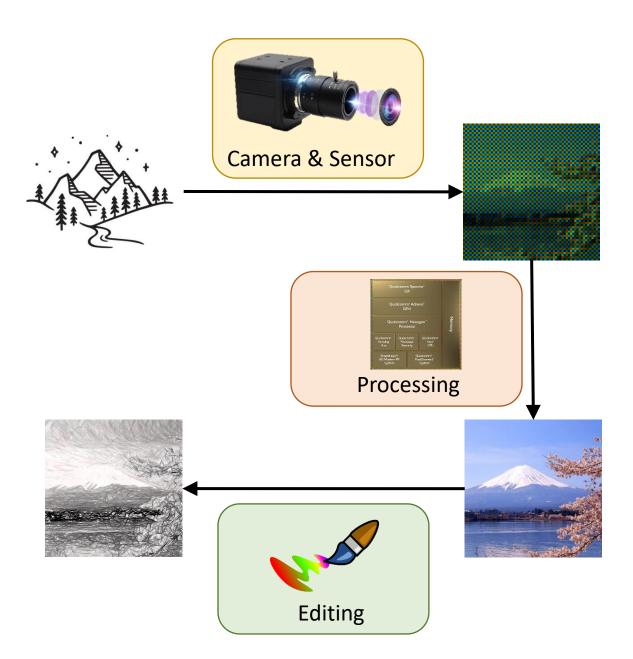




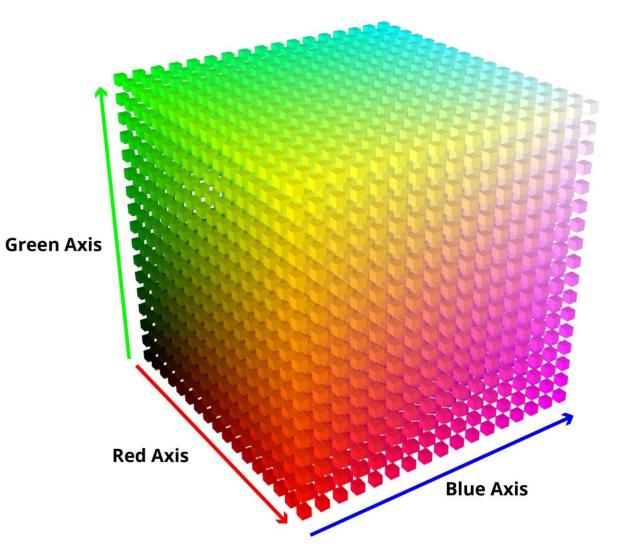
Wu et al,. "How to Train Neural Networks for Flare Removal", ICCV 2021

Overview

- **Capturing**: multiple source fusion
- Processing & editing
 - Training data: synthetic data
 - Network: combine classic image processing algorithm and machine learning

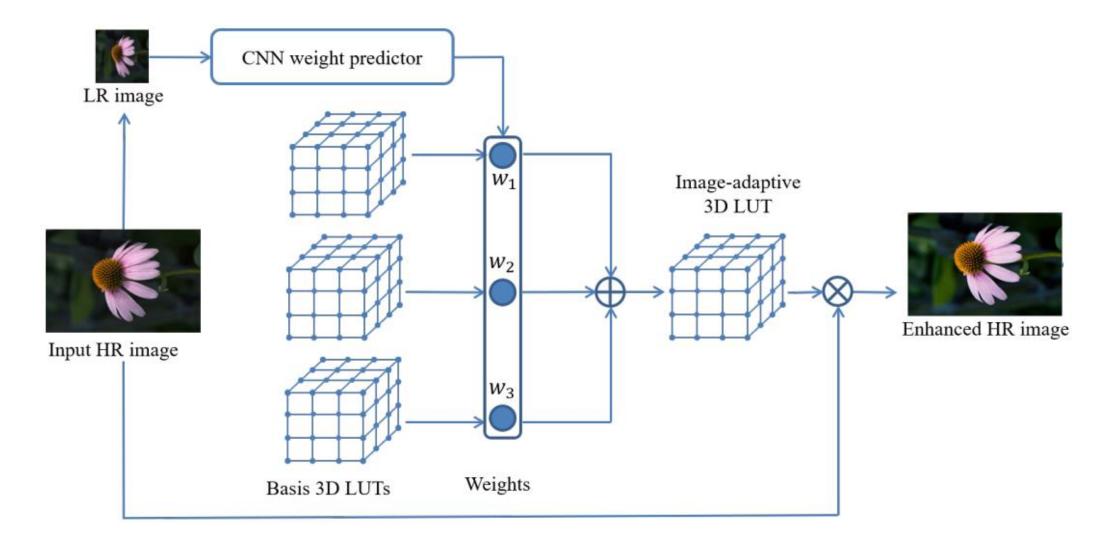


Representing point operation: 3D LUT



https://www.bromptontech.com/what-is-a-3d-lut/

Learning to enhance -> Learning 3D LUT

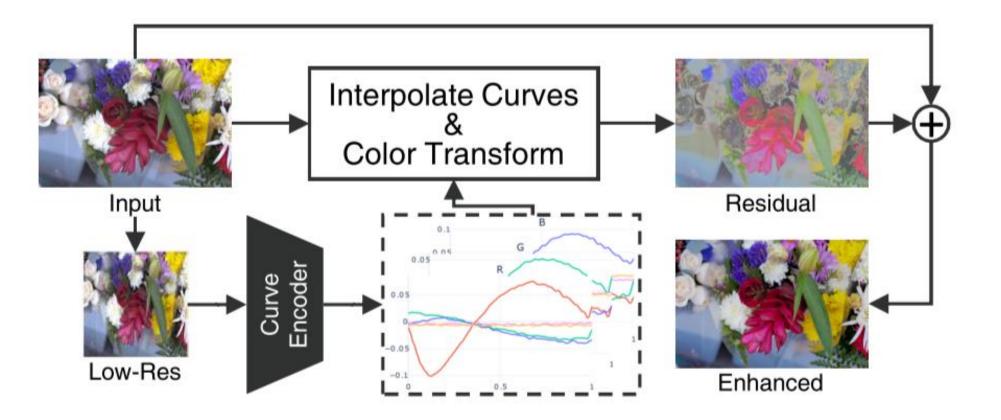


H. Zeng et al., "Learning Image-adaptive 3D Lookup Tables for High Performance Photo Enhancement in Real-time", T-PAMI, 2020

Learning 3D LUT significantly reduces the time cost

Resolution	1920×1080	3840×2160	6000×4000
Pix2Pix [49]	1.2e2	N.A.	N.A.
CycGAN [50]	5.6e2	N.A.	N.A.
DPE [7]	8.6e1	N.A.	N.A.
White-Box [9]	5.0e3	9.1e3	2.0e4
Dis-Rec [8]	2.5e4	1.1e5	3.3e5
UIE [11]	1.0e4	2.0e4	3.3e4
HDRNet [2]	4.5e1	2.1e2	5.9e2
UPE [10]	4.5e1	2.1e2	5.9e2
Ours	0.64	1.66	3.76

Image Enhancement: Using color tran. and global curve



Song et al, "StarEnhancer: Learning Real-Time and Style-Aware Image Enhancement", ICCV 2021

Direct prediction is expensive





Input

[PhotoWCT: Li et al., ECCV 2018] [WCT2: Yoo et al., ICCV 2019] [LST: Li et al., CVPR 2019]

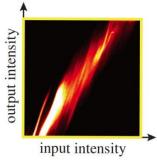
All of them are OOM when applied to 4MP image



Neural network

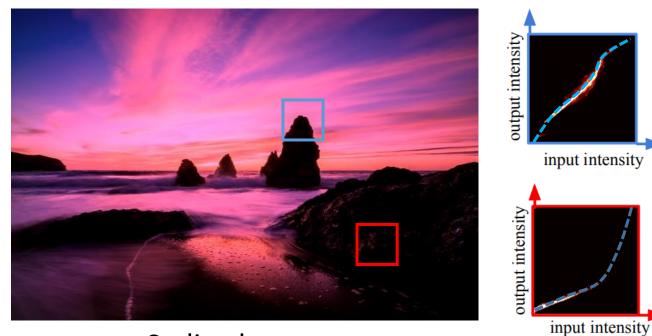
Stylized output

Can we approximate it using tone curves?



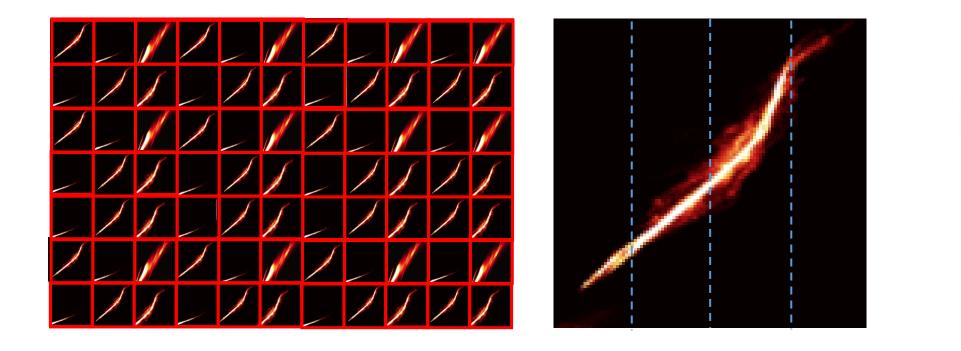


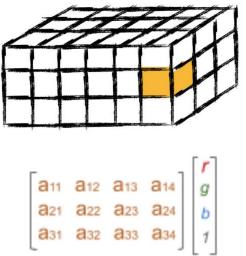
Input



Stylized output

Model a set of tone curves as bilateral grid

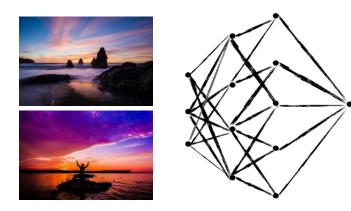


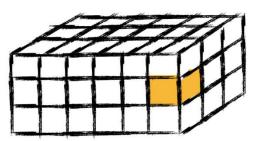


Bilateral grid

J. Chen, A. Adams, N. Wadhwa, S. Hasinoff, "Bilateral guided upsampling", 2017 M. Gharbi, J. Chen, J. Barron, S. Hasinoff, F. Durand, "Deep Bilateral Learning for Real-Time Image Enhancement", SIGGRAPH 2017

Style transfer using a set of tone curves







Tone curves baked in bilateral grid

Low resolution: 256x256

Full resolution: 4Kx3K



Output





Input

X. Xia, M. Zhang, T. Xue, Z. Sun, H. Fang, B. Kulis, J. Chen, "Joint bilateral learning for real-time universal photorealistic style transfer", ECCV 2020

Performance

Image Size	PhotoWCT	LST	$ WCT^2 $	Ours
512×512	$0.68 \mathrm{s}$	0.25s	$3.85\mathrm{s}$	< 5 ms
1024×1024	$1.51\mathrm{s}$	0.84s	6.13s	< 5 ms
1000×2000	$2.75\mathrm{s}$	OOM	10.94s	$< 5 \mathrm{ms}$
2000×2000	OOM	OOM	OOM	$< 5 \mathrm{ms}$
3000×4000	OOM	OOM	OOM	$< 5 \mathrm{ms}$

Latency

Mean Score	PhotoWCT	LST	WCT^2	Ours
Photorealism	2.02	2.89	4.21	4.14
Stylization	3.10	3.19	3.24	3.49
Overall quality	2.23	2.84	3.60	3.79

User study of visual quality





HDRnet tonemapping



12 megapixel 16-bit linear input (tone-mapped for visualization)

tone-mapped with HDR+ 400 - 600 ms

processed with our algorithm 61 ms, PSNR = 28.4 dB

M. Gharbi, J. Chen, J. Barron, S. Hasinoff, F. Durand, "Deep Bilateral Learning for Real-Time Image Enhancement", SIGGRAPH 2017

Used by Google Tensor Chip



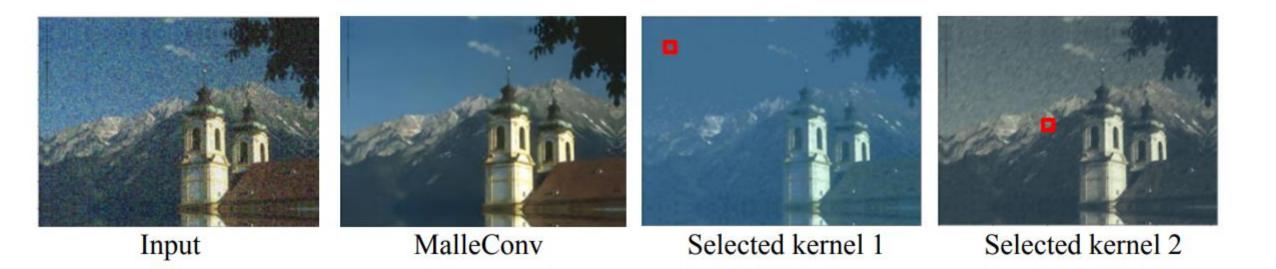
Google Tensor

The brand new chip designed by Google, custom-made for Pixel.



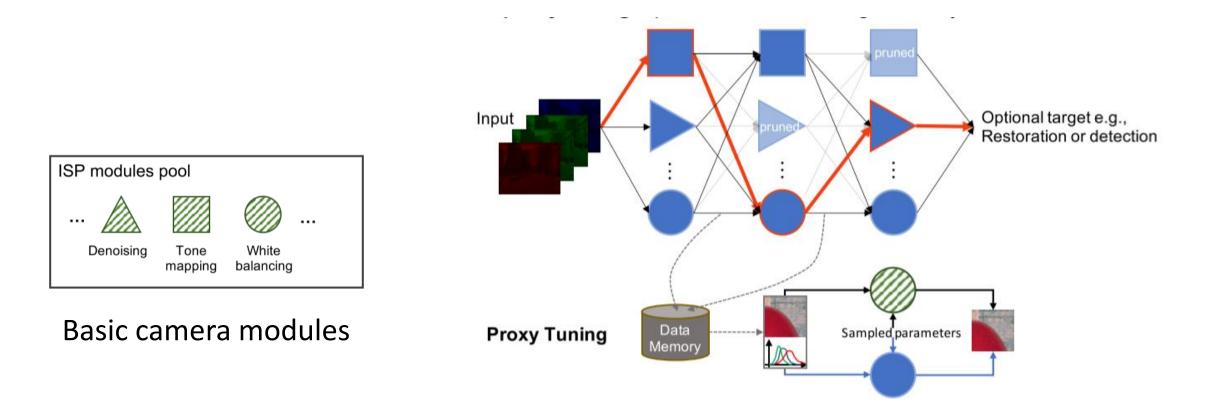


Denoising using spatially varying kernels



Jiang et al, "Fast and High-quality Image Denoising via Malleable Convolutions", ECCV 2022

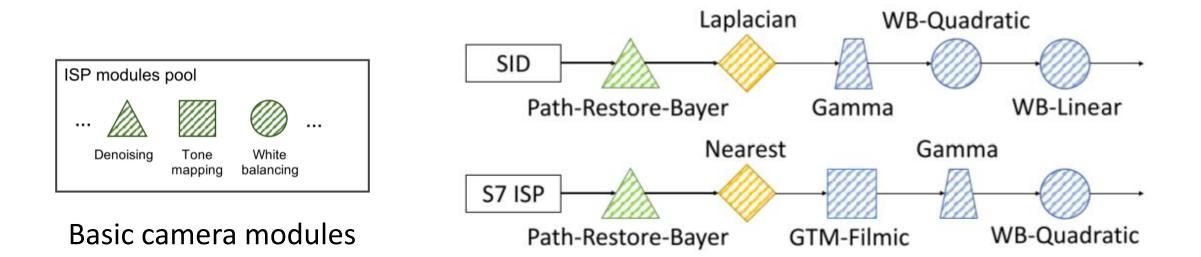
We can even learn to reorder different modules



Learn a task-specific pipeline

K. Yu et al, "ReconfigISP: Reconfigurable Camera Image Processing Pipeline", ICCV 2021

We can even learn to reorder different modules



Different task may need different pipelines

K. Yu et al, "ReconfigISP: Reconfigurable Camera Image Processing Pipeline", ICCV 2021

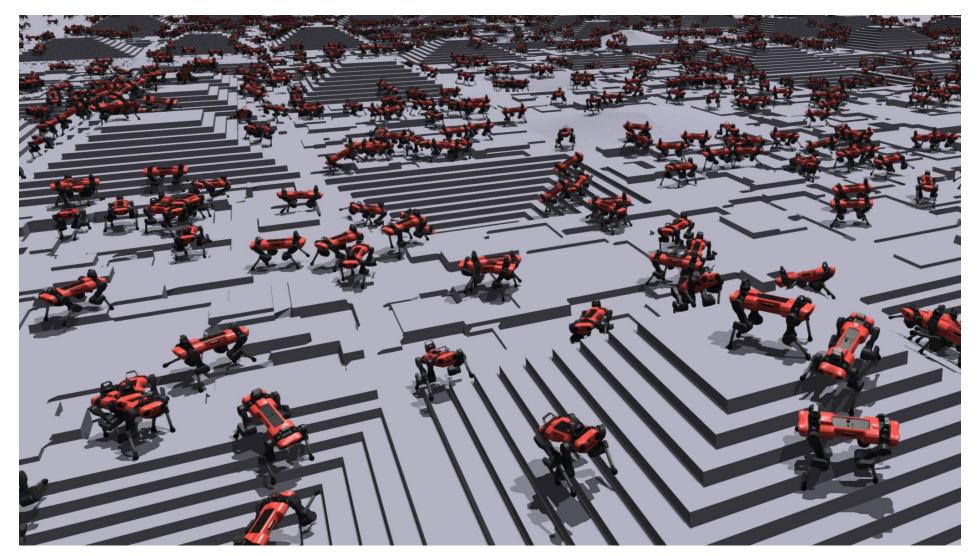
Future smart cameras research

Simulation is important to collect training data



Image credit: Tesla AI Day

Is there Isaac Gym for computational photography?



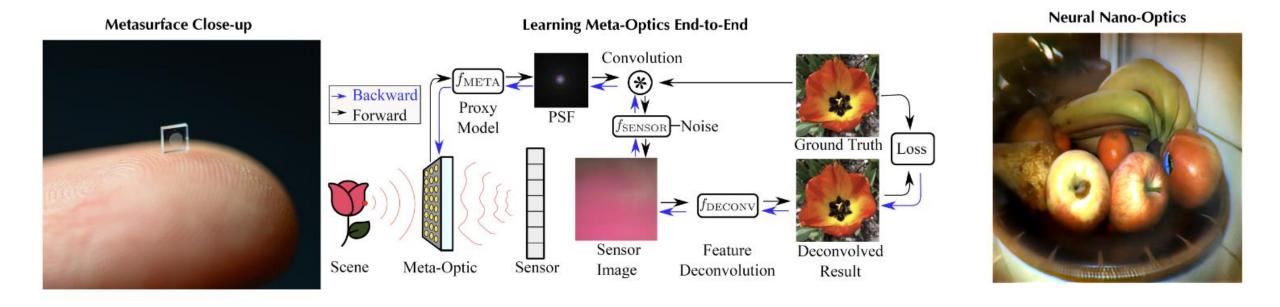
Issac Gym by NVIDIA, for robotic algorithm design



Computational Photography and Hardware

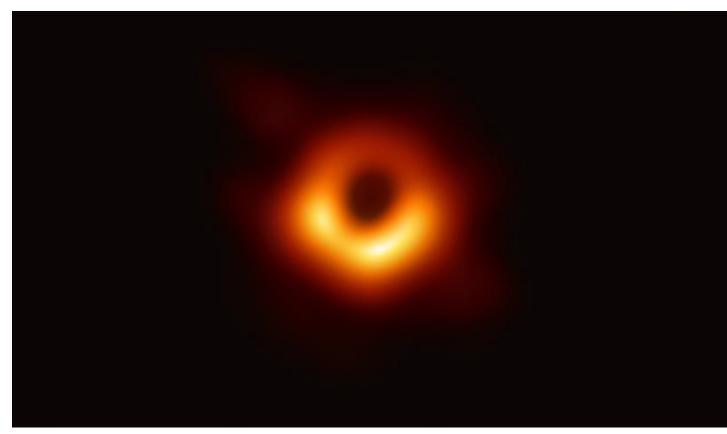
Image credit: <u>https://bit.ly/2mmFtKP</u>

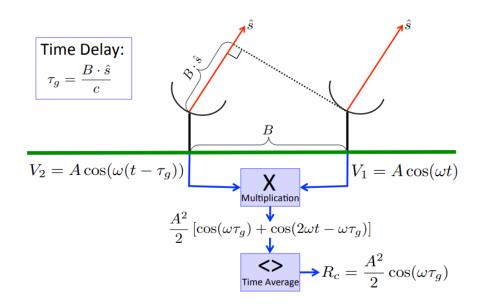
Joint lens and algorithm design



Tseng et al., "Neural nano-optics for high-quality thin lens imaging", 2021

Camera is not only for better selfies



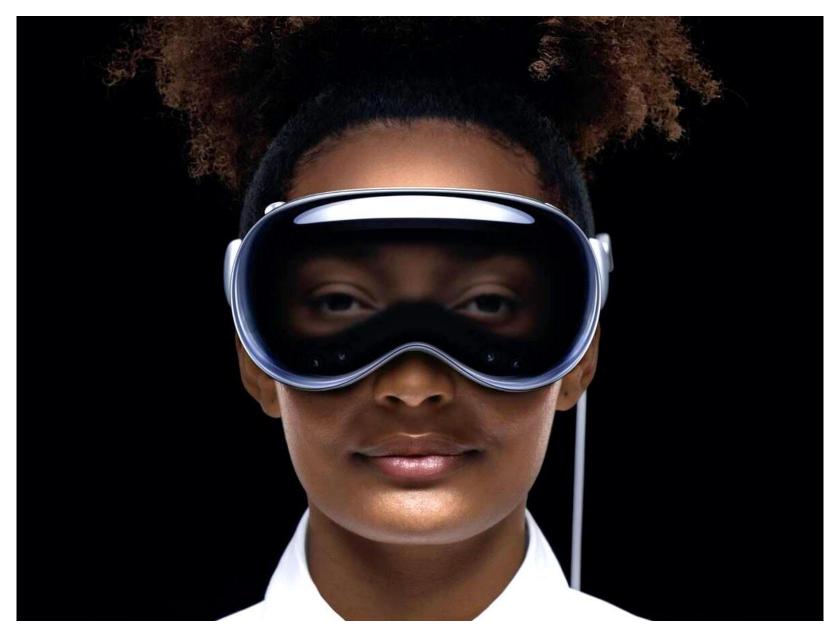


First black hole image [image credit: NASA]

VLBI image formation

K. Bouman, "Computational Imaging for VLBI Image Reconstruction", CVPR 2016

How VR may impact us

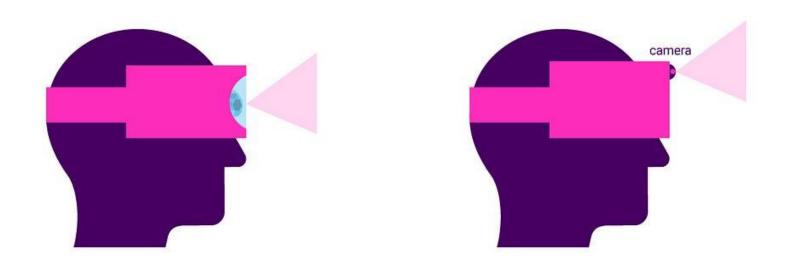


Can we capture more 3D content using our cameras?



B. Mildenhall et al., "NeRF: Representing Scenes as Neural Radiance Fields for View Synthesis", ECCV, 2020

Can cameras be as good as our eyes?

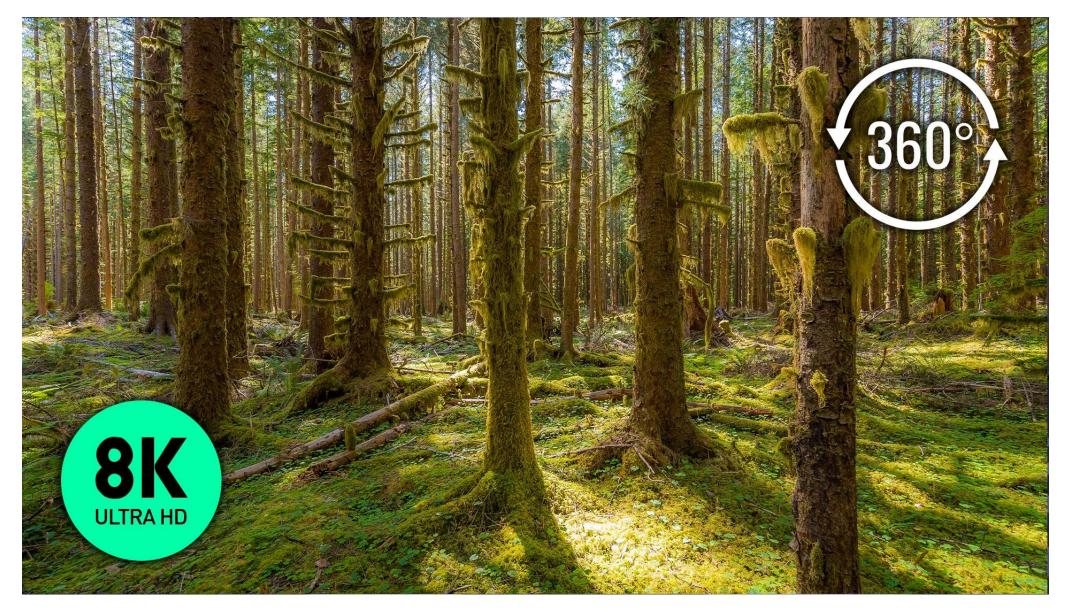


Optical see through displays

Video see through displays

https://uxdesign.cc/augmented-reality-device-types-a7668b15bf7a

Can our algorithms be as fast as to deal with 8K60fps?



AIGC and Computational Photography





Which one is real, which one is fake?

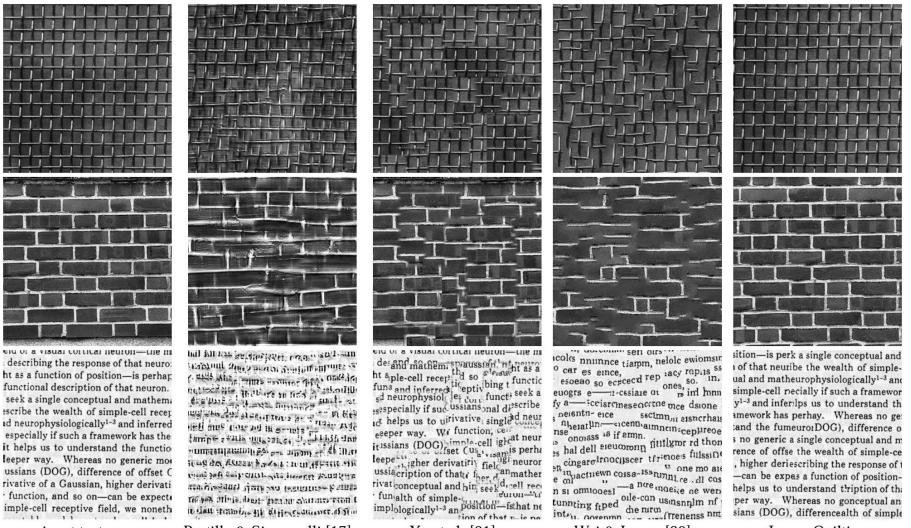
https://www.bilibili.com/video/BV16M4y1q7B5



Robin et al., "High-Resolution Image Synthesis with Latent Diffusion Models", CVPR 22.



Generated by Midjourney v5: <u>https://petapixel.com/2023/03/17/midjourney-v5-creates-photorealistic-images-and-even-does-hands-correctly/</u>



input texture

Portilla & Simoncelli [17]

Xu et.al. [21]

Wei & Levoy [20]

Image Quilting

A. Efros and W. T. Freeman, "Image quilting for texture synthesis and transfer", CG 2001

Do we even need a powerful lens?

Only less powerful camera hardware is needed in the future?

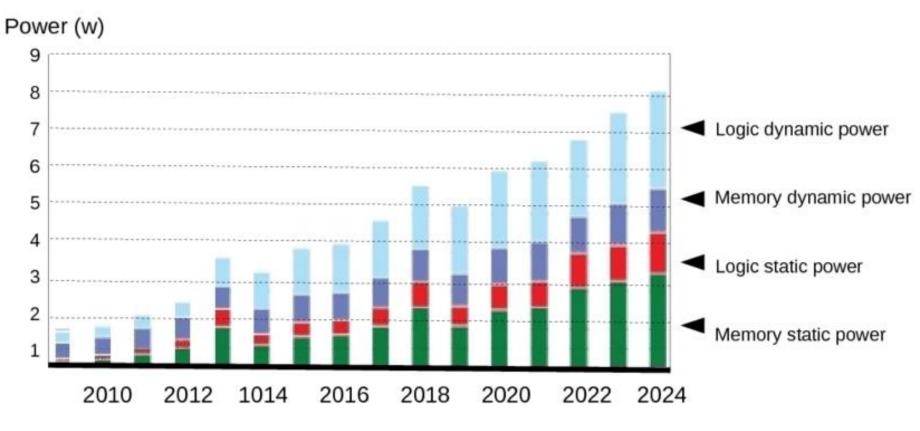


Cameras become more powerful in past 10y

Gap between academic research and industrial design



Industrial not only care quality, but also speed & power

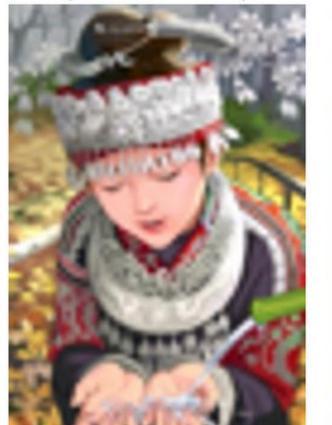


SoC consumer portable power consumption

Yahia Benmoussa, "Performance and Energy Consumption Characterization and Modeling of Video Decoding on Multicore Heterogenous Mobile SoC and their Applications"

High PSNR != Better Image

bicubic (21.59dB/0.6423)



SRResNet (23.53dB/0.7832)



SRGAN (21.15dB/0.6868)



L., Christian, et al. "Photo-realistic single image super-resolution using a generative adversarial network." CVPR. 2017.

Diff users may even have diff preferences



3 experts gave very different tunings

Image credit: Adobe 5K

It is even hard to describe what is best





Some photographers don't like oversmoothed image, and call it "**like oil painting**" Some photographers don't like HDR image, and call it "**Cartoon-look**"

http://barney-streit.squarespace.com/blog/2013/6/5/good-hdr-bad-hdr

Collaborators and acknowledgement



Bill Freeman

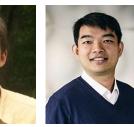
Fredo Durand







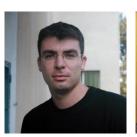




Ce Liu



Orly Liba



Miki Rubinstein





Jon Barron



Joseph Lim

Sam Hasinoff



Dillon Sharlet

Rahul Garg







Jiajun Wu

Xide Xia



Zheng Sun



Katie Bouman









Pratul Srinivasan

Ioannis Gkioulekas

Jian Wang

Qiurui He

Brian Kulis









Neal Wadhwa

Chengkai Zhang

Yun-Ta Tsai





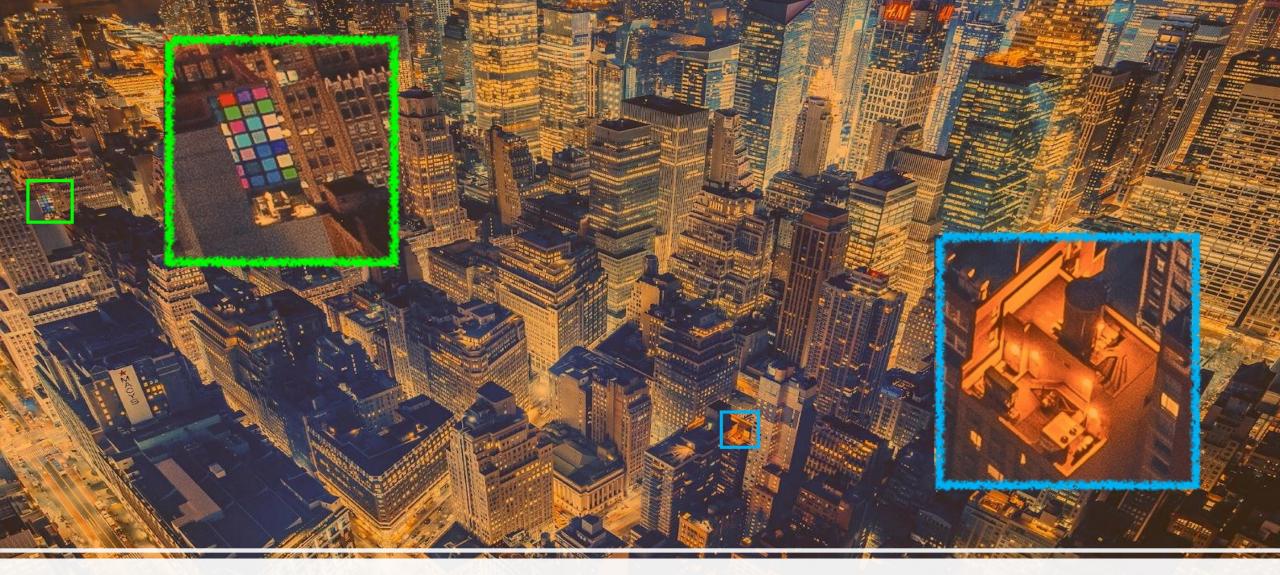
Shumian Xin





Simon Niklaus

Paul Debevec



Q&A